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The second derivative of $f(x)$, for $x = 0$, is given by $f''(x) = 2\sqrt{2} - 2\cos(2\sqrt{3}\ln x) + 4\sqrt{3}\sin(2\sqrt{3}\ln x)$. Thus: $f''(x_k) = 2\sqrt{2} - 2\cos \pi/4 + 4\sqrt{3}\sin \pi/4 = 2\sqrt{2} - 2\sqrt{2}/2 + 4\sqrt{3}\sqrt{2}/2 = 4\sqrt{6}$. Similarly $f''(y_k) = 2\sqrt{2} - 2\cos -\pi/4 + 4\sqrt{3}\sin -\pi/4 = 2\sqrt{2} - 2\sqrt{2}/2 - 4\sqrt{3}\sqrt{2}/2 = -4\sqrt{6}$. Hence, $\{x_k \mid k \geq 0\}$ is a sequence of nonsingular local minima, which evidently converges to x^* ,

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This is a thoroughly rewritten version of the 1999 2nd edition of our best-selling nonlinear programming book. New material was included, some of the old material was discarded, and a large portion of the remainder was reorganized or revised. The number of

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Characterization of Primal and Dual Optimal Solutions
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elements of the underlying theory of linear programming,

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2016. Dynamic Programming and Optimal Control, Vols. I and II, Athena Scientific, 1995, (4th Edition Vol. I, 2017, 4th Edition Vol. II, 2012). Abstract Dynamic Programming, 2nd Edition Athena Scientific, 2018; click here for a free .pdf copy of the book.

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